

Exercise 3 Throwing a ball

file: Exercise3_Balltrajectory.m HA 4.12.2018

(a)

```
clear; close all;format compact  
g=9.81;  
v=10;  
al=35; % Use sind,cosd, or al=(pi/180)*al and sin, cos
```

Find t-value, where ball hits the ground

```
Tend=10; % Wild guess  
t=linspace(0,Tend,1000);  
h=v*t*sind(al)-1/2*g*t.^2; % sind(x), x degrees  
h(end)<0 % If yes, then Tend is sufficiently large.
```

```
ans = logical
```

```
1
```

This is the numerical way, solving the zeros by hand is even easier, see below. (One student did this way :-))

```
negind=find(h<0,1) % Find first meeting condition (h<0)
```

```
negind = 118
```

```
% Could use logical indexing also:  
% lastposind=sum(h>=0) % sum([1 1 1 1,...,1,0 0 0 ...])  
%  
Tend=t(negind) % Update Tend
```

```
Tend = 1.1712
```

```
t=linspace(0,Tend,1000); % Update t  
h=v*t*sind(al)-1/2*g*t.^2; % Update h  
negind=find(h<0,1) % Update negind
```

```
negind = 999
```

```
% Check  
hsignchange=h([negind-1 negind])
```

```
hsignchange = 1x2  
0.0031 -0.0036
```

```
% Yes, indeed  
maxerr=t(2)-t(1) %
```

```

maxerr = 0.0012

sameas=Tend/1000           % Same as this.

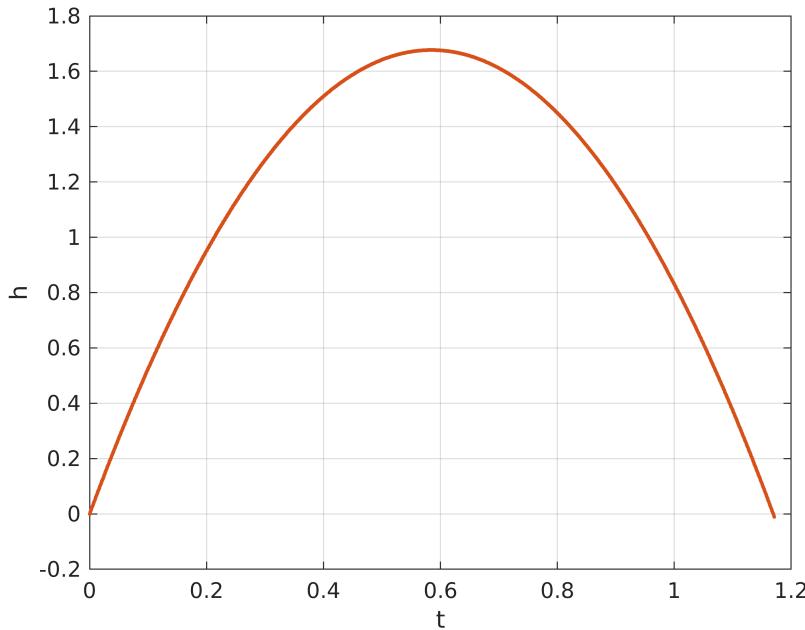
sameas = 0.0012

```

```

plot(t,h,t,h,'.');grid on
xlabel('t');ylabel('h');shg

```



```

%
% Using zoom sufficiently many times, one gets: h=0, for t=1.16937
% Note: plot uses linear interpolation, which gives very good
% approximation on small intervals, so the accuracy obtained by
% zooming is much better than the distance of t-points suggests.
%
```

Solve the 2nd degree equation numerically

Remember Matlab's representation of polynomials.

```
coeff=[-g/2 v*sind(al) 0]
```

```

coeff = 1x3
-4.9050    5.7358      0

```

```

format long
hzero=roots(coeff)

```

```

hzero = 2x1
      0

```

```
1.169370920185619
```

```
format short
%{
coeff =
-4.9050      5.7358      0
hzero =
          0
1.169370920185619
%}
% Hence all the 6 digits of the graphical method were correct.
```

The easiest way of course is to write the solution by hand:

$$h = 0 \Leftrightarrow v \sin(\alpha) = gt/2,$$

hence:

$$t_0 = 2v \sin(\alpha)/g$$

```
format long
Tend=2*v*sind(al)/g
```

```
Tend =
1.169370920185619
```

```
format short % back t default
% Showing that all digits given by "roots" are correct.
% Everything works fine!!
% One could also practice the symbolic toolbox, but let this be enough.
```

Max height:

```
t=linspace(0,Tend,1000);
h=v*t*sind(al)-1/2*g*t.^2;
[maxh,maxind]=max(h) % Could use find also, but this is easiest,I guess.
```

```
maxh = 1.6768
maxind = 500
```

```
max_t=t(maxind)
```

```
max_t = 0.5841
```

```
x=v*cosd(al)*t;
max_x=x(maxind) % x-value for max(h) (perhaps was not asked)
```

```
max_x = 4.7847
```

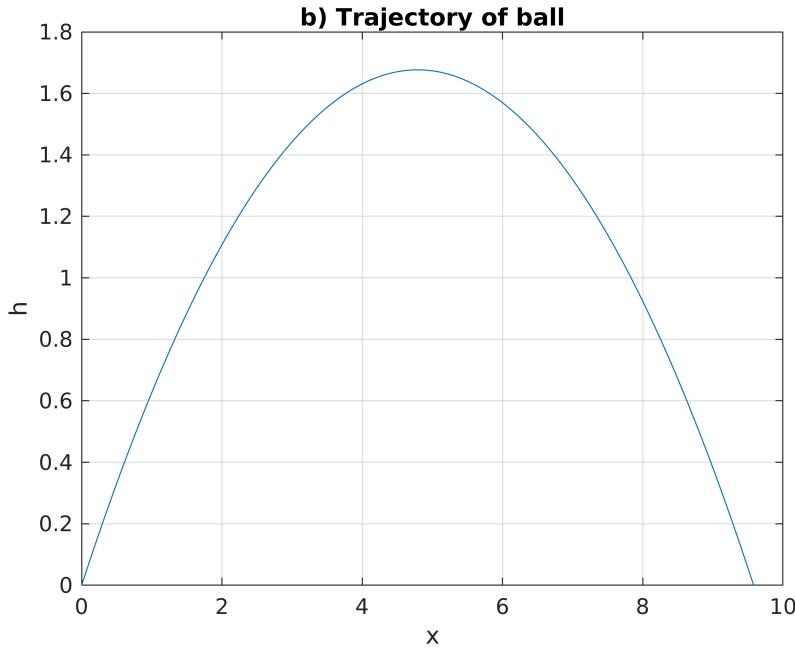
(b)

Same values as in a) Plot the ball's trajectory, i.e. the curve $(x(t), h(t))$.

```

figure(2);clf
t=linspace(0,Tend); % Enough to use 100 points.
x=v*cosd(al)*t;
h=v*sind(al)*t-1/2*g*t.^2;
plot(x,h);grid on
title('b) Trajectory of ball')
xlabel('x');ylabel('h');shg

```



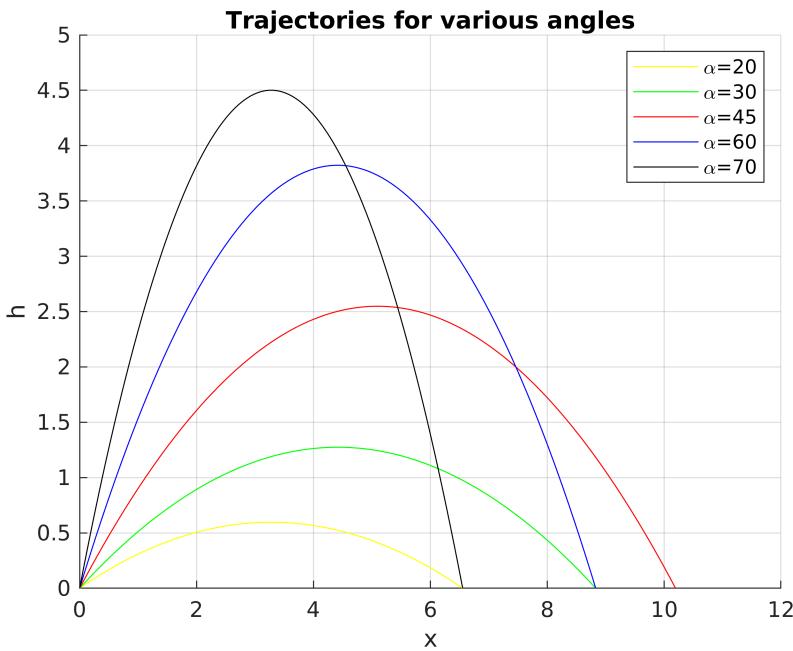
(c) Trajectories for various angles(al)

Same v and various α

```

figure(3);clf
hold on
colors=['ygrbk']; % In case you want to control the colors
% "yellow,green,red,blue,black"
c=0;
for al=[20 30 45 60 70]
coeff=[-g/2 v*sind(al) 0];
Tend=max(roots(coeff));
t=linspace(0,Tend);
x=v*cosd(al)*t;
h=v*sind(al)*t-1/2*g*t.^2;
c=c+1;
plot(x,h,colors(c))
end
title('Trajectories for various angles')
legend('\alpha=20','\alpha=30','\alpha=45','\alpha=60','\alpha=70')
grid on; xlabel('x');ylabel('h');shg

```



(d) Trajectories for $\alpha = 45$, with various initial velocities

Same v and various al

```

figure(4);clf
g=9.81;
al=45;
hold on
colors=[ 'mrgrbk' ]; % "magenta,green,red,blue,black"
c=0;
for v=10:2:18
    coeff=[-g/2 v*sind(al) 0];
    Tmax=max(roots(coeff));
    t=linspace(0,Tmax);
    x=v*cosd(al)*t;
    h=v*sind(al)*t-1/2*g*t.^2;
    c=c+1;
    plot(x,h,colors(c))
end
title('Trajectories for \alpha=45, various init. velocities')
legend('v=10','v=12','v=14','v=16','v=18')
grid on;xlabel('x');ylabel('h');shg

```

